

# Couplage de clustering et d'analyses de sensibilité pour les modèles à sorties multivariées

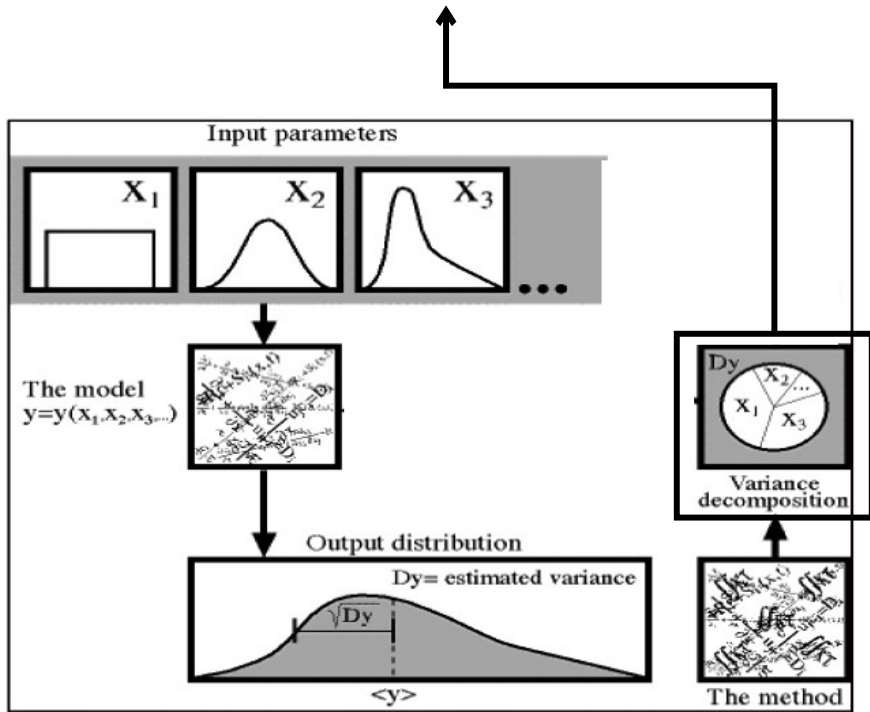
Sébastien Roux<sup>1</sup>, Patrice Loisel<sup>1</sup>, Samuel Buis<sup>2</sup>

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<sup>2</sup> INRAE, UMR EMMAH, Avignon, France,

# Global Sensitivity Analysis: Variance-Based methods

Parts of variance explained by the different parameters



From Saltelli et al (2001)

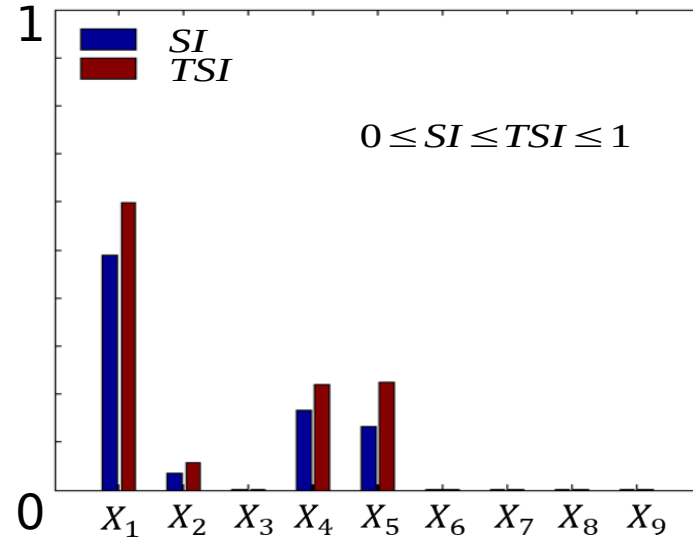
## Sobol' Indices:

$X_i$  alone

$X_i$  and its interactions

$$SI(X_i) = \frac{V(E(Y|X_i))}{V(Y)}$$

$$TSI(X_i) = 1 - \frac{V(E(Y|X_{-i}))}{V(Y)}$$

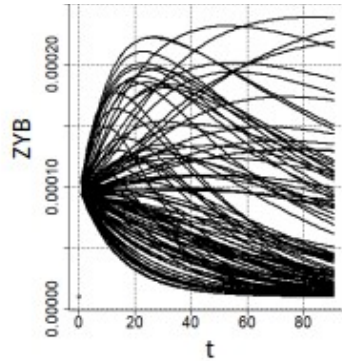


## Motivation

- ⇒ Which parameters drive the model outputs toward different behaviors / regions in the model output space?

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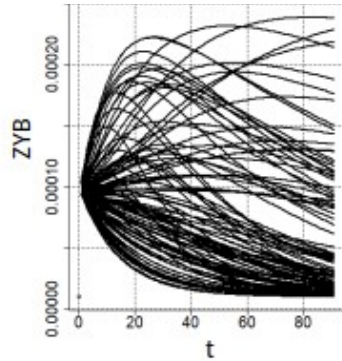
⇒ Which parameters drive the model outputs toward different behaviors / regions in the model output space?



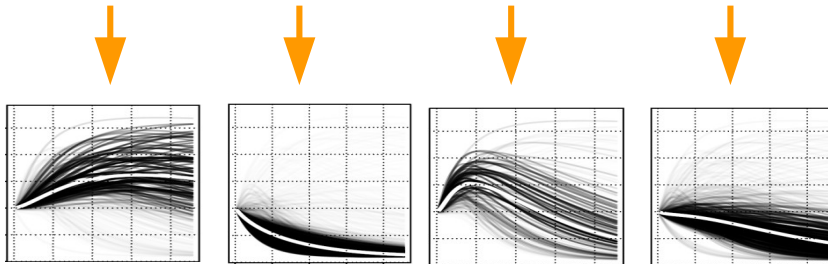
nd  
multivariate

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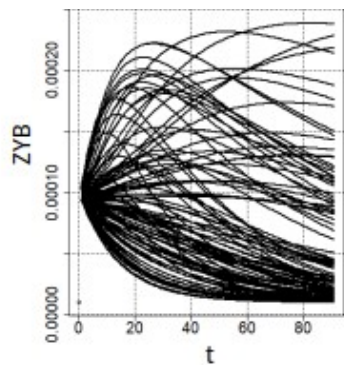


nd  
multivariate

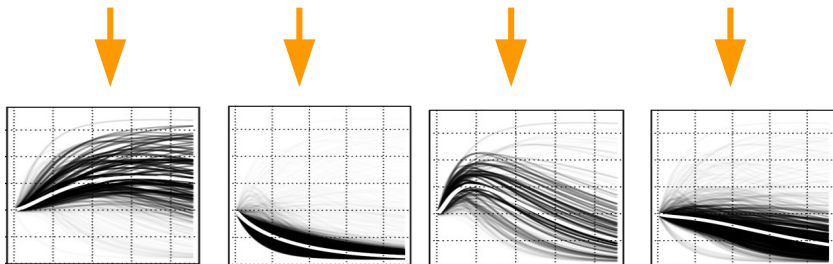


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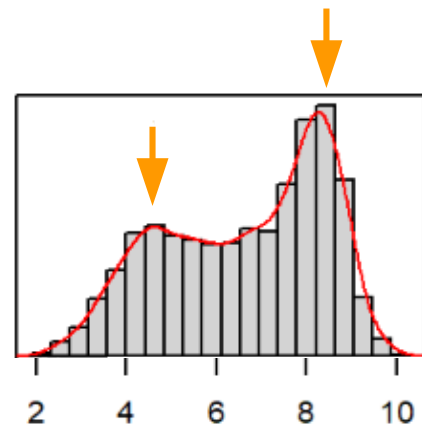
⇒ Which parameters drive the model outputs toward different behaviors / regions in the model output space?



nd  
multivariate



1d  
bimodal



# Cluster-based GSA : Principle

## Combines clustering methods

**=> reveal and characterize multiple distinct behaviors of the model outputs**

## and variance-based methods

**=> identify in a robust way parameters and interactions that drive these different behaviors**

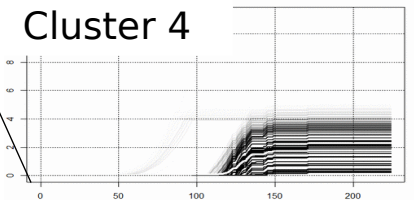
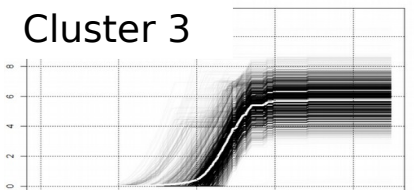
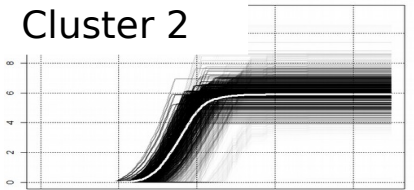
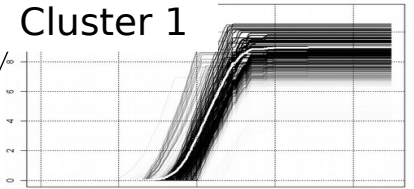
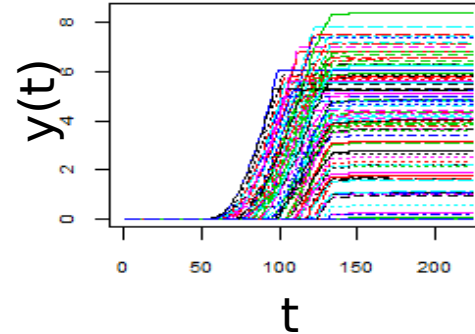
# Cluster-based GSA : scalar membership functions

output = Membership Functions (MF)

$$y^i(t) \rightarrow [u_1^i, \dots, u_K^i]$$

$u_k^i$ : level of membership of object i  
to cluster k

$$\sum_{k=1}^K u_k^i = 1$$



Roux, S., Buis, S., Lafolie, F., & Lamboni, M. (2021).

Cluster-based GSA: Global sensitivity analysis of models with temporal or spatial outputs using clustering. *Environmental Modelling & Software*,



# Cluster based GSA indices

$$y^i(t) \rightarrow [u_1^i, \dots, u_K^i]$$

- Sensitivity indices on membership functions  
=> Which parameters (or interactions) drive the model outputs toward a targeted cluster?

$$SI_k(X_j) = \frac{V(E(u_k|X_j))}{V(u_k)}$$

$$TSI_k(X_j) = 1 - \frac{V(E(u_k|X_{-j}))}{V(u_k)}$$

- Sensitivity indices on membership function differences  
=> Which parameters (or interactions) drive the model outputs from one cluster to another?

$$SI_{kl}(X_j) = \frac{V(E((u_k - u_l)|X_j))}{V(u_k - u_l)}$$

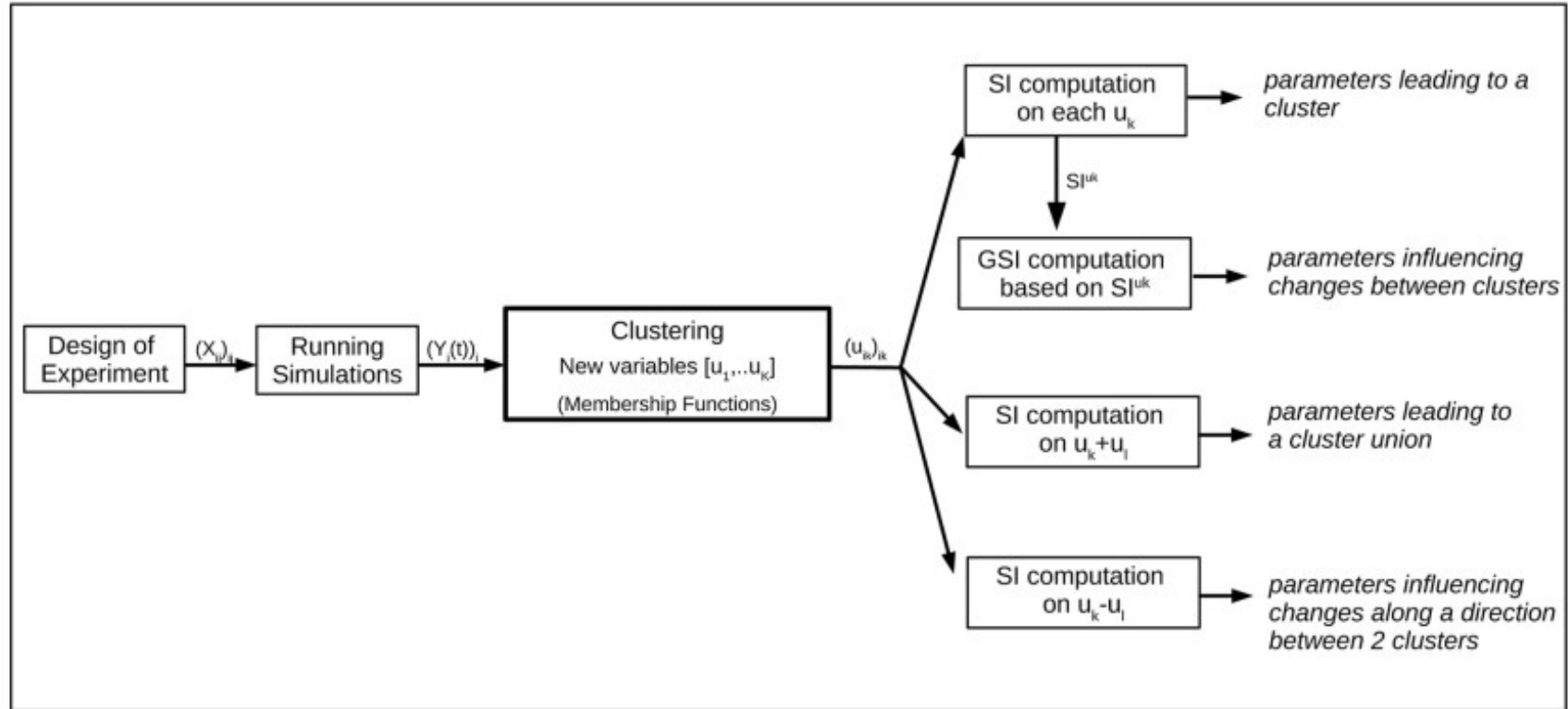
$$TSI_{kl}(X_j) = 1 - \frac{V(E((u_k - u_l)|X_{-j}))}{V(u_k - u_l)}$$

- Aggregated indices on the vector of membership functions  
=> Which parameters (or interactions) globally impact changes between clusters

$$SI(X_j) = \frac{\sum_{k=1}^K V(u_k) SI_k(X_j)}{\sum_{k=1}^K V(u_k)}$$

$$TSI(X_j) = \frac{\sum_{k=1}^K V(u_k) TSI_k(X_j)}{\sum_{k=1}^K V(u_k)}$$

# Cluster-based GSA : workflow



Roux, S., Buis, S., Lafolie, F., & Lamboni, M. (2021).

Cluster-based GSA: Global sensitivity analysis of models with temporal or spatial outputs using clustering. *Environmental Modelling & Software*,

# Possible use of cluster-based sensitivity indices

- Using ClustSIs, we can associate sensitivity indices to output space partitions
- There are 3 general ways of using cluster-based indices

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(expertise-driven clustering)

- **Optimized Partitions**

-> **Data-driven clustering**  
ClusterBased GSA  
Optimization based on Y

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ClusterBased GSA  
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-> **Sensitivity-driven clustering**  
Optimization based on Y and X  
(typically using  $SI_1(X_i)$ )

# Possible use of cluster-based sensitivity indices

- Using ClustSIs, we can associate sensitivity indices to output space partitions
- There are 3 general ways of using ClustSIs

• **Prior partitions**  
(expertise-driven clustering)

**CHARACTERIZATION**

-> **Data-driven clustering**  
ClusterBased GSA  
Optimization based on Y

• **Optimized Partitions**

**EXPLORATION**

-> **Sensitivity-driven clustering**  
Optimization based on Y and X  
(typically using  $SI_1(X_i)$ )



# Sensitivity-driven clustering

- Objectives :
  - **revealing behaviors (ie regions of the output space)** most (or very much) impacted by variations of a parameter (or a group or an interaction,..) using an optimization procedure
  - expressing **graphically** the sensitivity of the input factors (or a group or an interaction,..) on the output, including in the case of MV outputs

# Sensitivity-driven clustering

- 1D « analytical example »
- 2D (numerical with different approaches )
- ND (numerical)

# Optimized sensitive partitioning in 1D

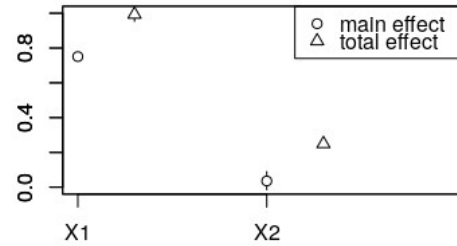
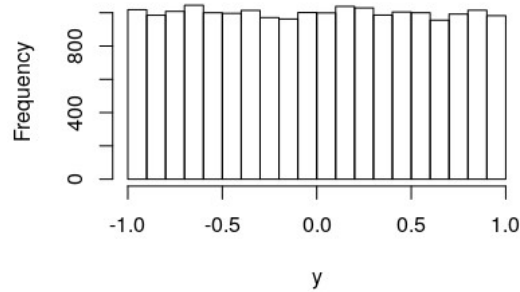
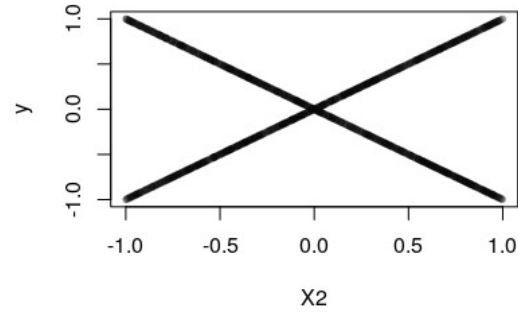
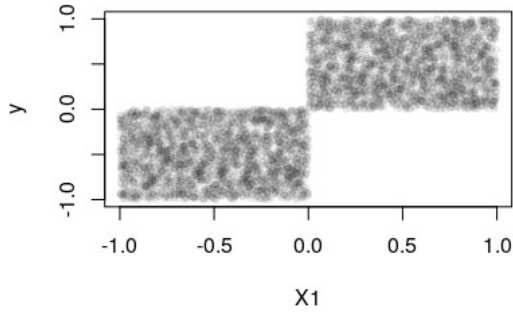
- we restrict to the study to binary partitions A,B of  $[0,1]$
- many possible situations depending on connexity



- binarization with 2 connected components  $\Rightarrow$  parameterization of by a single cutting value  $yc$
- binarization with 3 connected components  $\Rightarrow$  parameterized by a two cutting values  $yc1$  and  $yc2$

# 1D « analytical example »

$$Y(x_1, x_2) = \text{sign}(X_1) \cdot |X_2|$$
$$x_1 \sim U[-1, 1]$$
$$x_2 \sim U[-1, 1]$$



# 1D « analytical example »

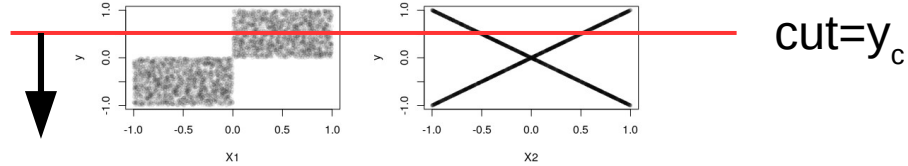
$$Y(x_1, x_2) = \text{sign}(X_1) \cdot |X_2|$$

$$x_1 \sim U[-1, 1]$$

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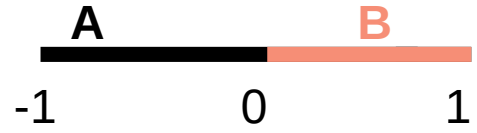
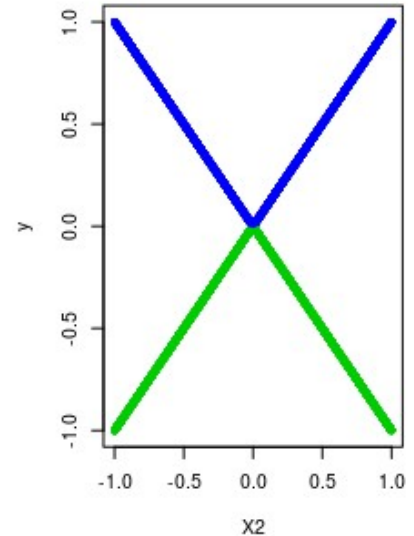
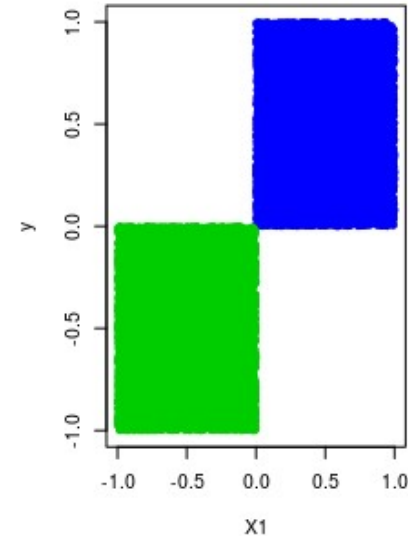
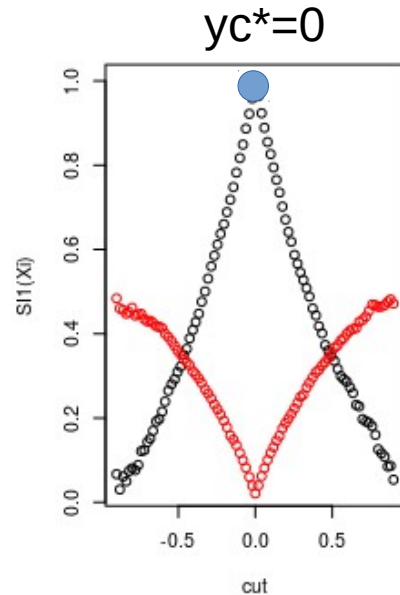
Binarization with 2

Connected components:  $\tilde{Y}^{y_c}(X_1, X_2) = \mathbb{1}_{Y(X_1, X_2) \leq y_c}$



$SI_1(X_1)$  for every cutting values  $y_c$   
 $SI_1(X_2)$  for every cutting values  $y_c$

$$SI_k(X_j) = \frac{V(E(u_k | X_j))}{V(u_k)}$$



# 1D « analytical example »

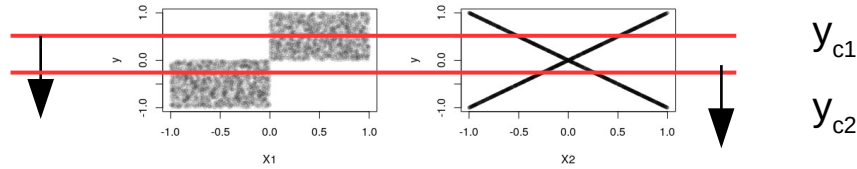
$$Y(x_1, x_2) = \text{sign}(X_1) \cdot |X_2|$$

$$x_1 \sim U[-1, 1]$$

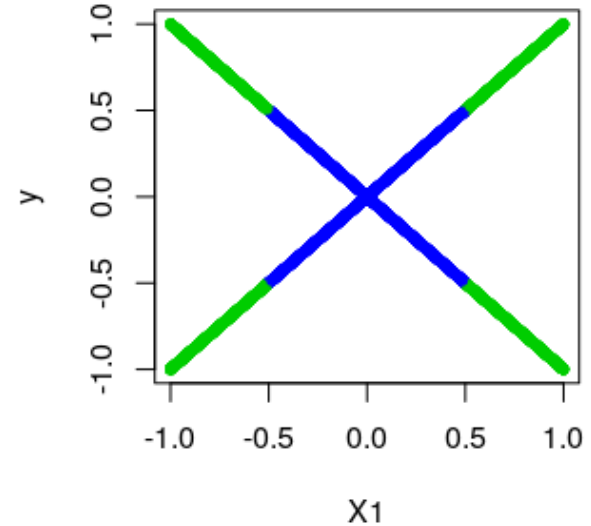
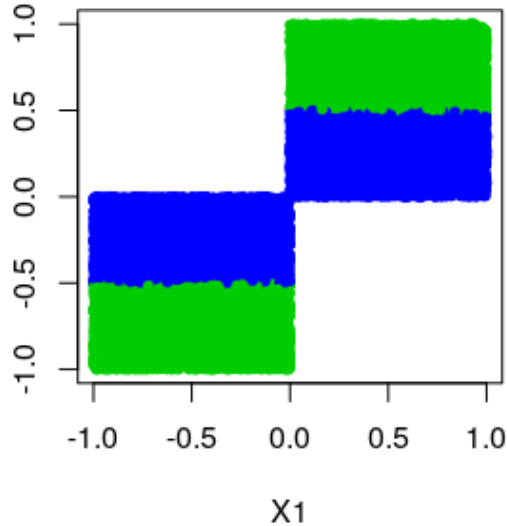
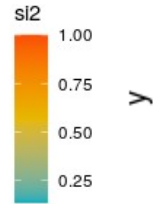
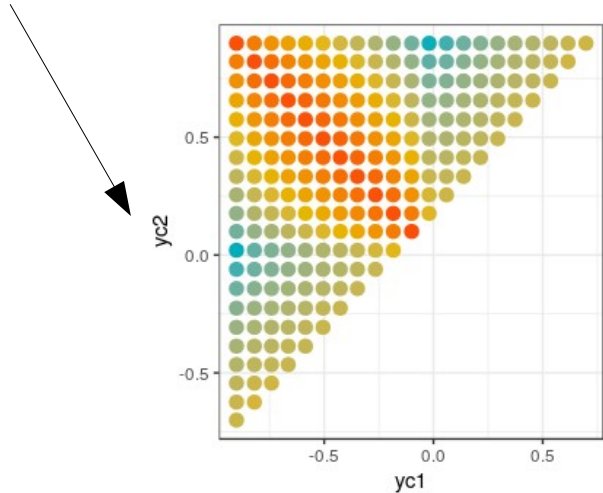
$$x_2 \sim U[-1, 1]$$

Binarization with 3  
Connected components:

$$\tilde{Y}^{y_{c1}, y_{c2}}(X_1, X_2) = \mathbb{1}_{Y(X_1, X_2) \in [y_{c1}, y_{c2}]}$$



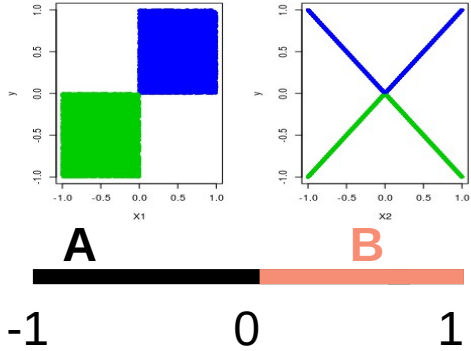
$SI_1(X_2)$  for every cutting values  $y_{c1}, y_{c2}$



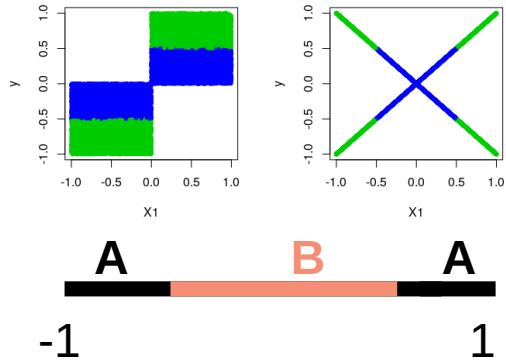
# 1D « analytical example »

$$Y(x_1, x_2) = \text{sign}(X_1) \cdot |X_2|$$
$$x_1 \sim U[-1, 1]$$
$$x_2 \sim U[-1, 1]$$

X1



X2



- Possibility to solve analytically
- Optimal partition depends on the parameter X1 or X2
- Optimum found even if the the space of partitions has not been completely explored (as SI=1 is optimal)
- We can have  $SI_{C^*} > SI$  (clustSI2\*=1, SI2=0)
- Optimal partitions can have more than 2 connected components
- The optimal partition in not unique

# 2D numerical example

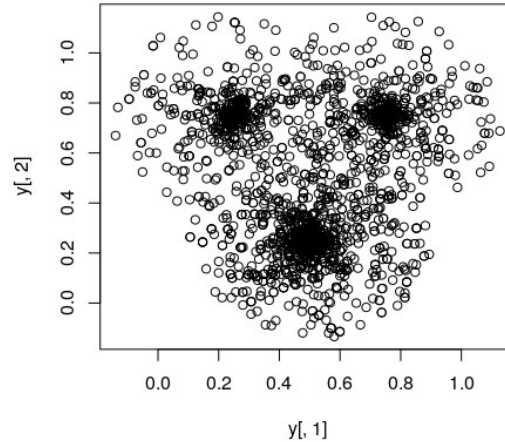
$$Y=(Y1,Y2) = f(X1,X2,x3,X4)$$

3 centers

$X1, X2$  : choice of center

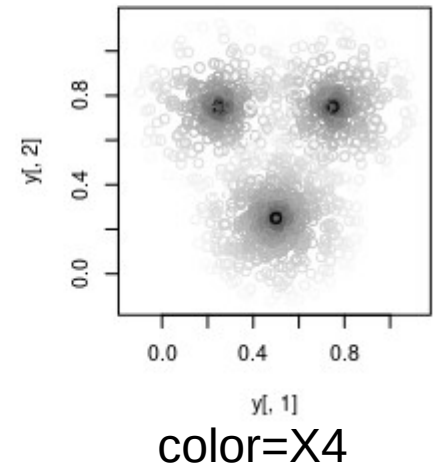
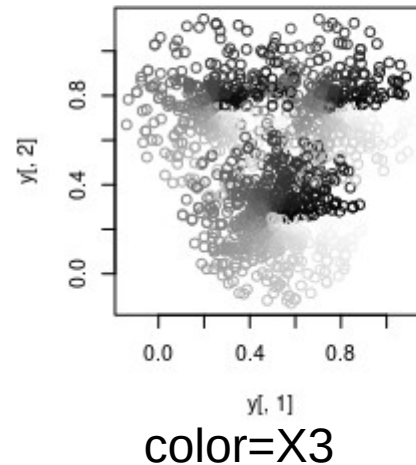
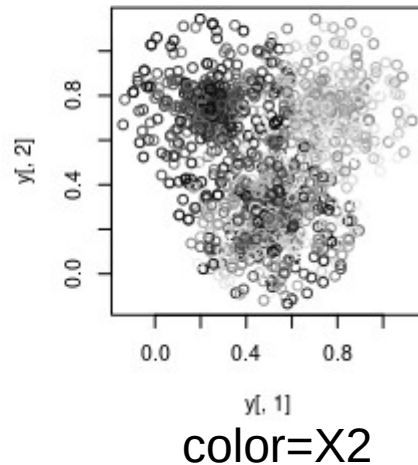
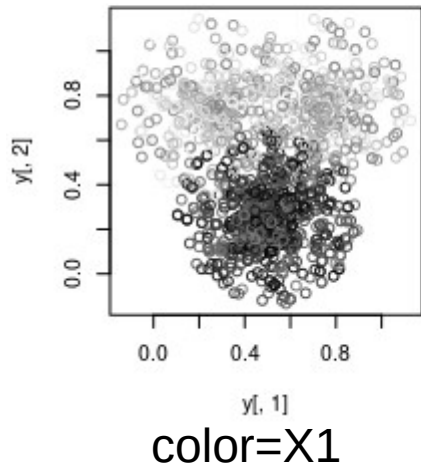
$X3$  : angle

$X4$  : distance from center



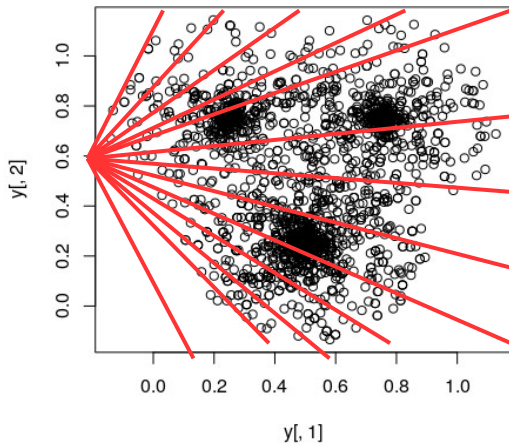
```
test2d_1 = function(x)
{
  cy = cent_y[1+as.numeric(x[1]>0.5)]
  if (cy==0.25)
    cx=0.5
  if (cy==0.75)
    cx=cent_x[1+ as.numeric(x[2]>0.5)]

  y1 = cx + 0.4* cos(2*pi*x[3])*x[4]^3
  y2 = cy + 0.4* sin(2*pi*x[3])*x[4]^3
  return(c(y1,y2))
}
```



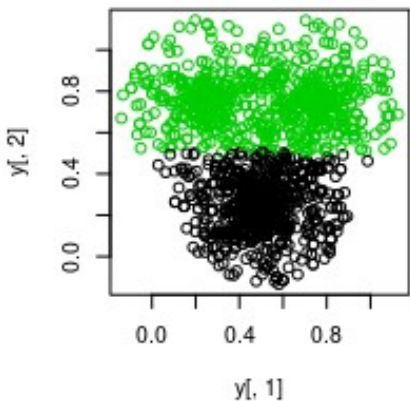


# 2D partitioning: connected binarization with straight lines

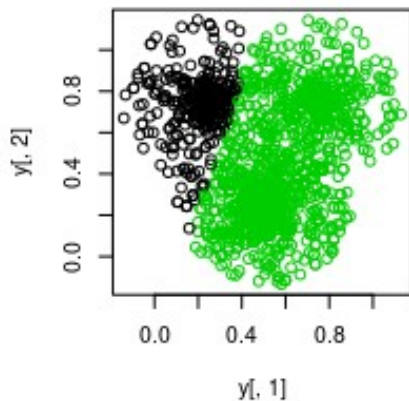


- Boundary discretization :  $n$  pts per border
- complexity:  $6.n^2$
- $N=7 \Rightarrow 294$  splitting

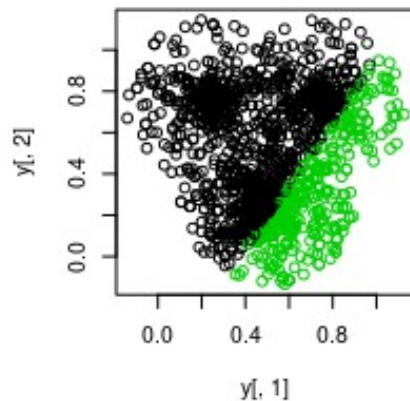
SI1\_1 = 0.896



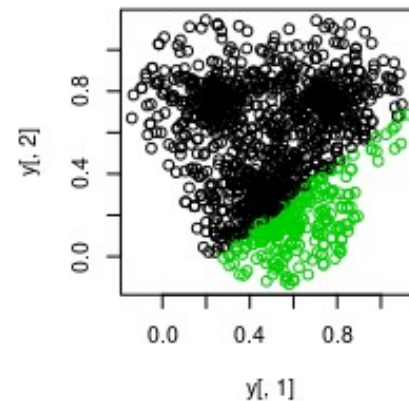
SI1\_2 = 0.346



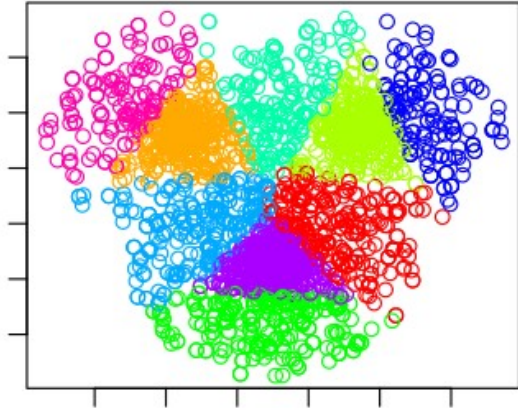
SI1\_3 = 0.316



SI1\_4 = 0.328



# 2D (and nD) partitioning: non-connected partitioning SI1 criterion

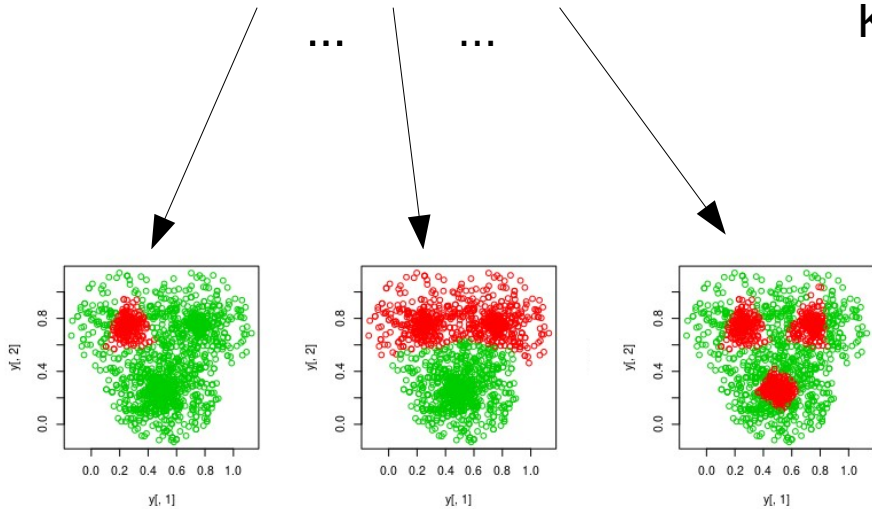


- **Principle of the algorithm for SI/TSI criteria :**
  - => Clustering of the outputs into K clusters
  - => Generate all partitions [1..K] into 2 sets
  - => Compute SI/TSI criteria for each binarization

- Nb :  $2^{(K-1)}$ 
  - K=10 : Nb= 512
  - K=20 : Nb= 524288

⇒ solve the issue of getting non connected set  
⇒ very flexible (various SI-based criteria, adding constraints)  
⇒ limited spatial resolution (K..)

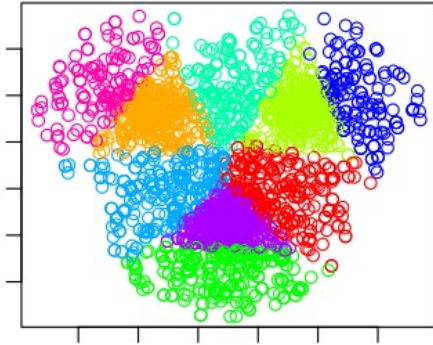
⇒ can handle MV output (providing the clustering does)



# 2D (and nD) partitioning: non-connected partitioning

## SI1 criterion

K=9



- **Principle of the algorithm for SI/TSI criteria: (sensitivity indices on Membership functions)**

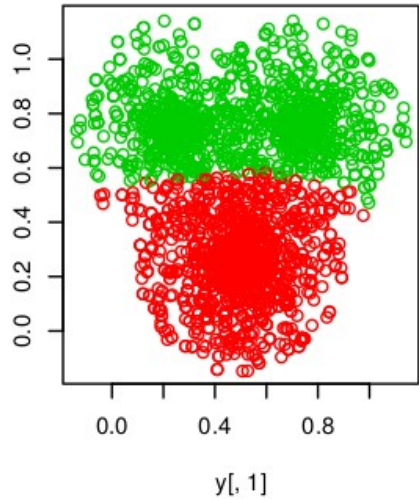
=> Clustering of the outputs into K clusters

=> Generate all partitions [1..K] into **2 sets**

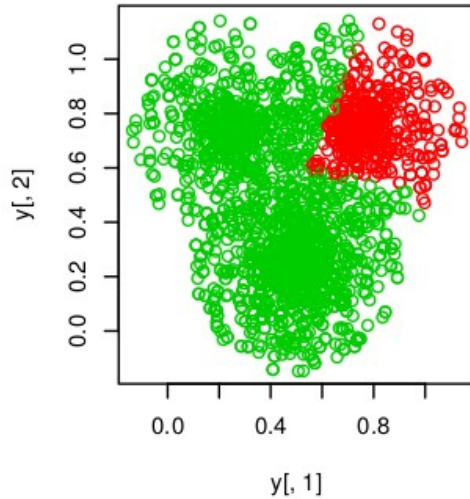
=> Compute SI/TSI criteria for each binarization

$$SI_k(X_j) = \frac{V(E(u_k|X_j))}{V(u_k)}$$

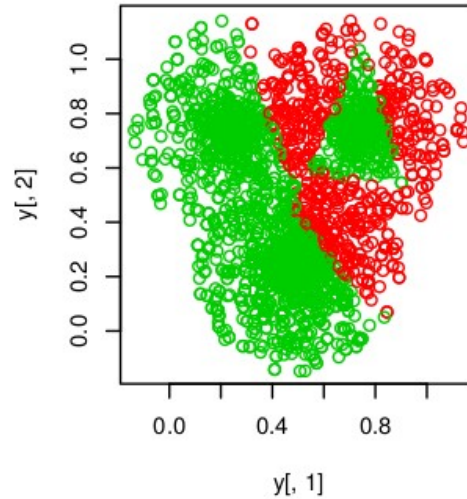
$S^*_1 = 0.866$



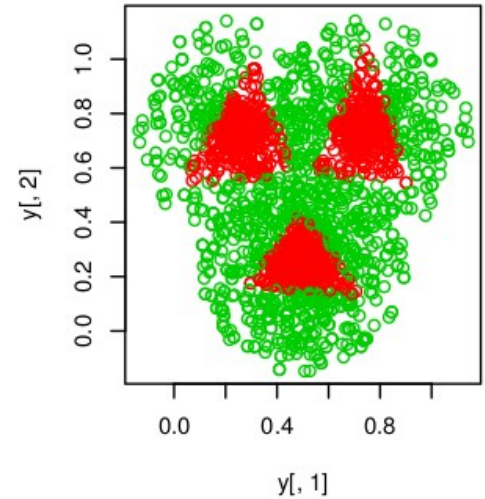
$S^*_2 = 0.315$



$S^*_3 = 0.116$



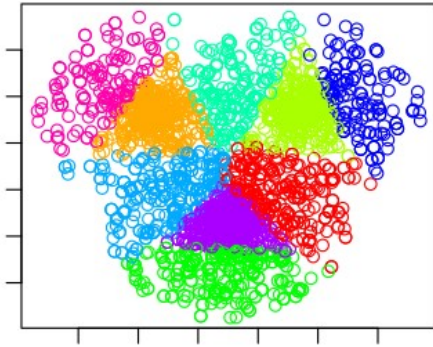
$S^*_4 = 0.763$



# 2D (and nD) partitioning: non-connected partitioning

## Other criterion : “neutral class”

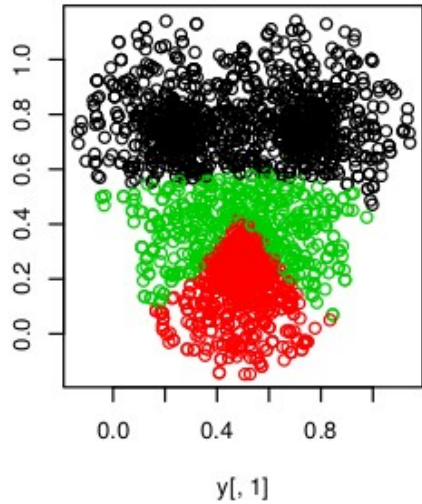
K=9



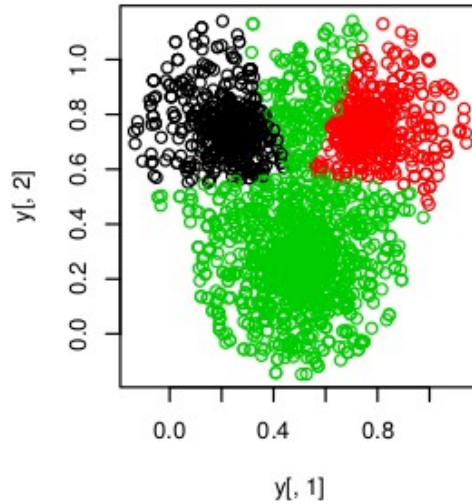
- Principle of the algorithm using ‘neutral class’ (SI/TSI criteria on MF differences)
- => Clustering of the outputs into K clusters
- => Generate all partitions [1..K] into 3 sets
- => Compute SI/TSI criteria for each set using  $u_1-u_2$

$$SI_{kl}(X_j) = \frac{V(E((u_k - u_l) | X_j))}{V(u_k - u_l)}$$

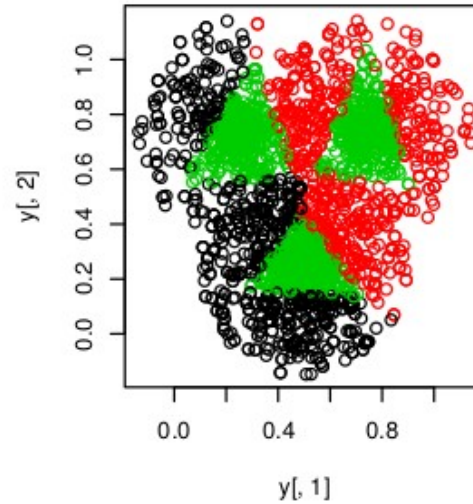
dS\_1 = 0.856



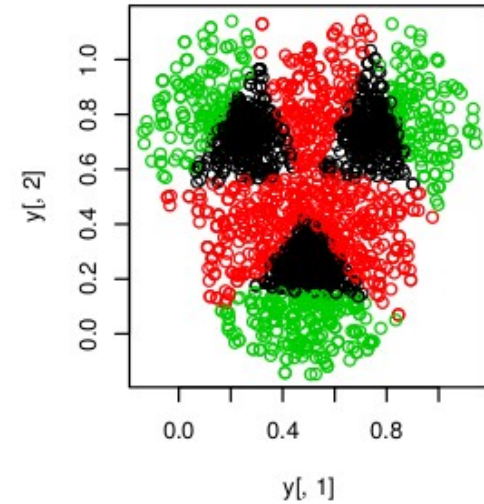
dS\_2 = 0.457



dS\_3 = 0.168



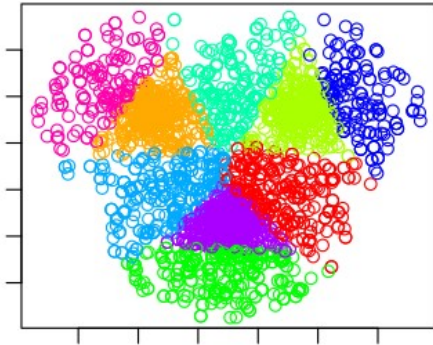
dS\_4 = 0.730



# 2D (and nD) partitioning: non-connected partitioning

## Other criterion : "GSI"

K=9



- **Principle of the algorithm**
- => Clustering of the outputs into K clusters
- => Generate all partitions [1..K] into 2-3-4-5 sets
- => Compute GSI criteria for each set

$$SI(X_j) = \frac{\sum_{k=1}^K V(u_k) SI_k(X_j)}{\sum_{k=1}^K V(u_k)}$$

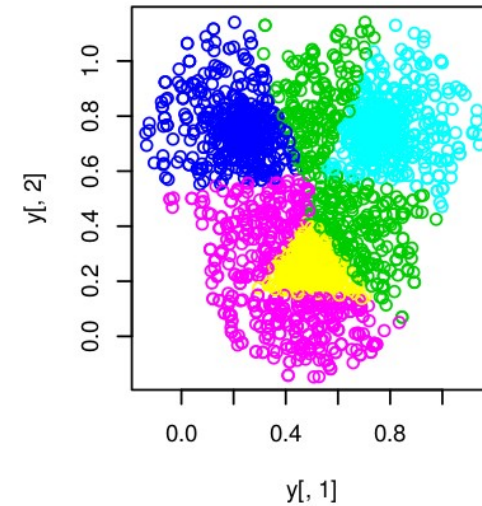
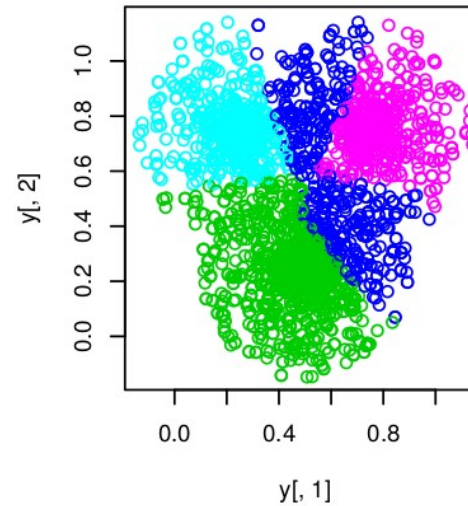
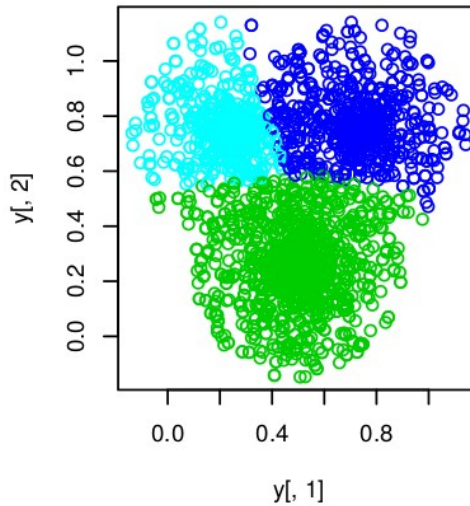
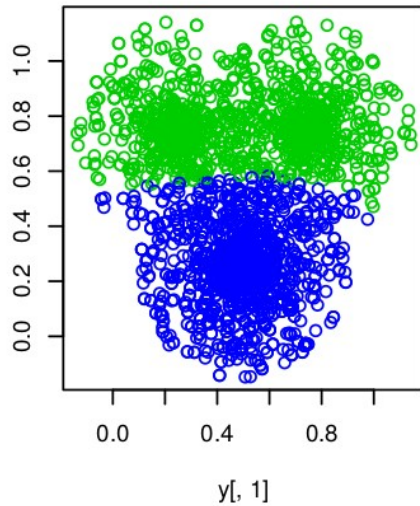
***Studying GSI for (X1,X2) and 2-3-4-5 sets***

Kpart=2 GSI\_12 = 0.872

Kpart=3 GSI\_12 = 0.850

Kpart=4 GSI\_12 = 0.696

Kpart=5 GSI\_12 = 0.542



# 2D (and nD) partitioning: non-connected partitioning

## Algorithm improvement for SI1 criterion

⇒ *Keeping the exhaustive step (seems necessary to handle non connectivity)*

⇒ *Improving the pre-processing step by using properties of the criterion*

We consider a set of elementary patches  $C_k$  (region of the output space)

We consider the conditional distribution of  $X_i$  for  $Y$  in  $C_k$

We compute **the associated histograms** for a given discretization of  $X_i$  into bins

The SI1 based clustering criterion writes

$$S_C = \frac{n_x}{\sum_{j=1}^{n_x} h_j^C (N - \sum_{j=1}^{n_x} h_j^C)} \sum_{i=1}^{n_x} \left( h_i^C - \frac{1}{n_x} \sum_{j=1}^{n_x} h_j^C \right)^2$$

# 2D (and nD) partitioning: non-connected partitioning

## Algorithm improvement for SI1 criterion

⇒ *Keeping the exhaustive step (seems necessary to handle non connectivity)*

⇒ *Improving the pre-processing step by using properties of the criterion*

Let's consider two patches  $C_k, C_{k'}$  and their associated histograms  $H_k, H_{k'}$

Let's suppose that  $H_k, H_{k'}$  are highly correlated

Let's denote  $(C^*, -C^*)$  the optimal partition built from the  $(C_k)$

Then

Either  $C_k$  and  $C_{k'}$  belongs to  $C^*$

$C_k$  and  $C_{k'}$  belongs to  $-C^*$

# 2D (and nD) partitioning: non-connected partitioning

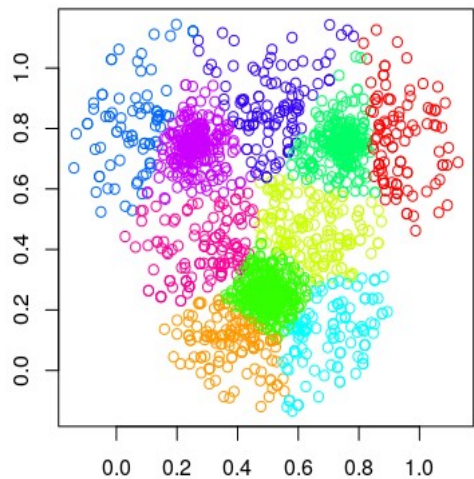
## Algorithm improvement for SI1 criterion

- ⇒ *Keeping the exhaustive step (seems necessary to handle non connectivity)*
- ⇒ *Improving the pre-processing step by using properties of the criterion*

- High resolution clustering of the output space into K cluster (e.g. 150)
- **New : Aggregation of clusters based on histogram correlation**
  - K' metapatches
- Generate all partitions [1..K'] into 2 sets
- Compute SI/TSI criteria for each binarization

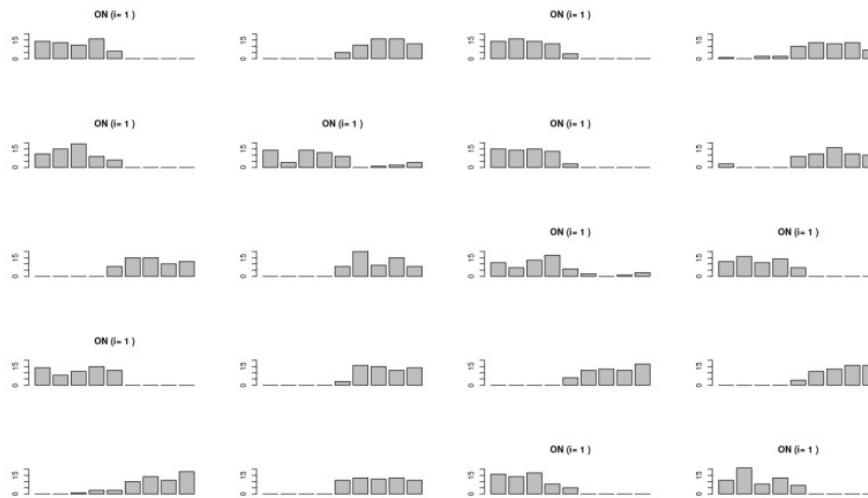


# Hierarchical clustering of elementary histograms

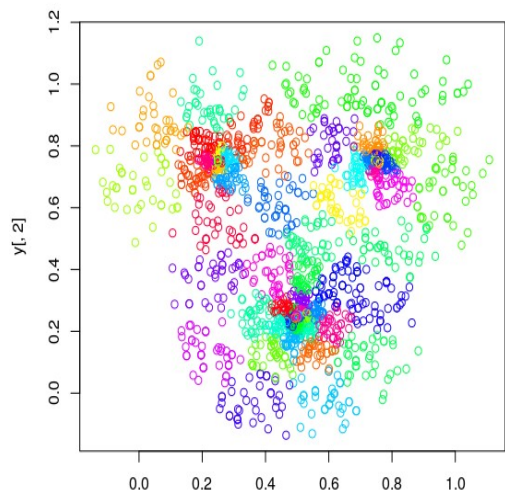


All elementary histograms ; ON= contributing to optimal

X1

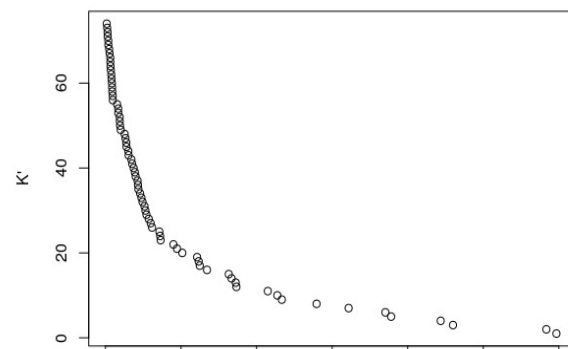
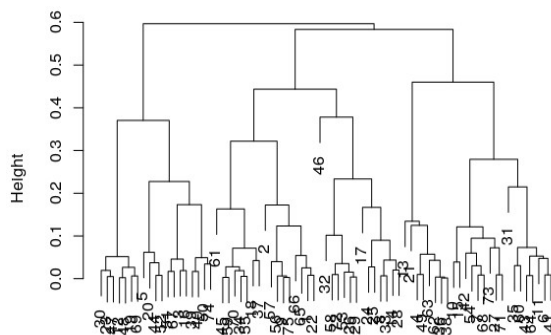


K=10

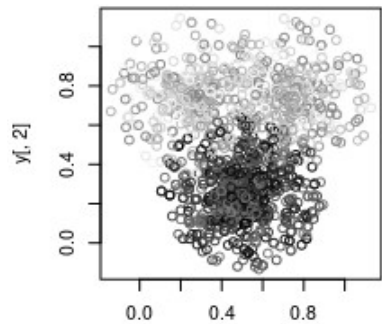


Cluster Dendrogram

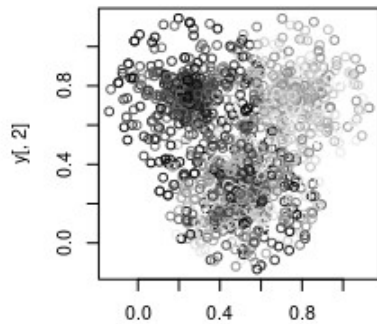
X3



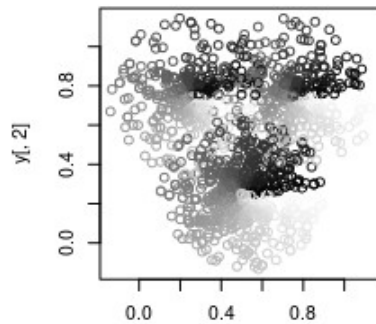
# Results



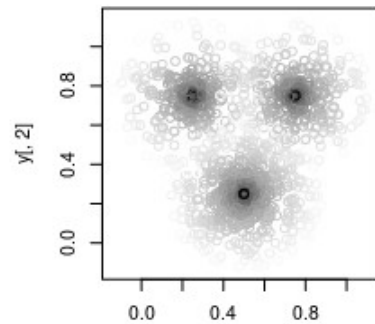
color=X1



color=X2



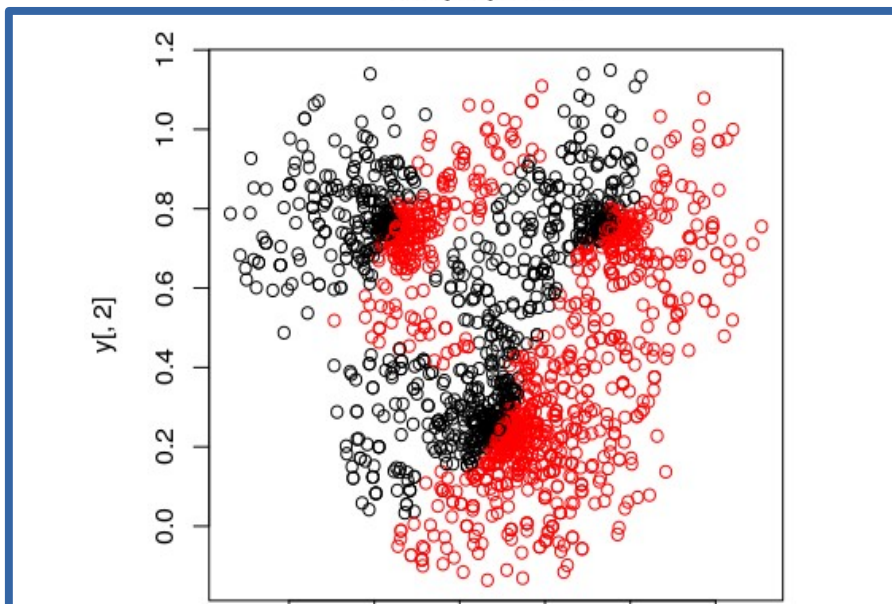
color=X3



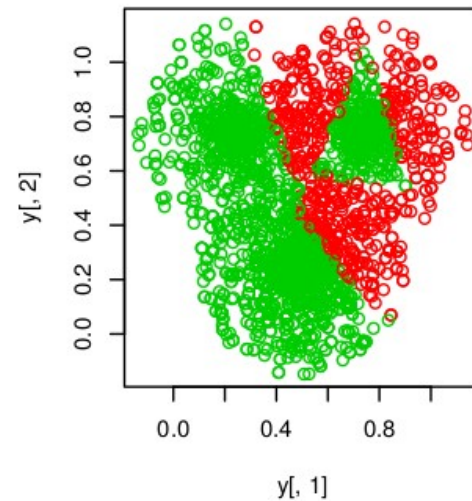
color=X4

**X3**  
**K=150**  
**Cut=0.2**  
**K'=16**

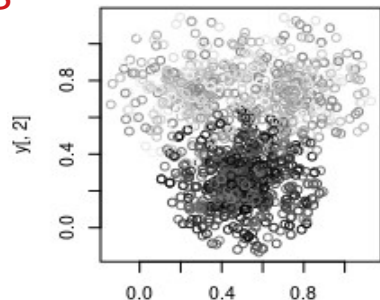
$SI^*(X3)=0.695$



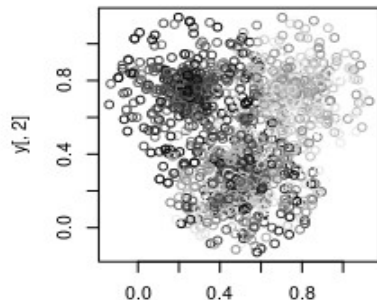
$S^*_3 = 0.116$



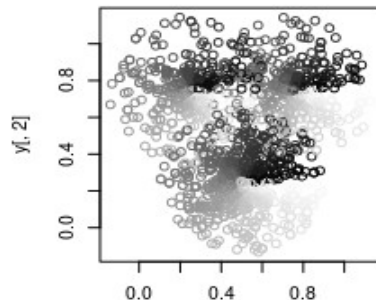
# Resultats



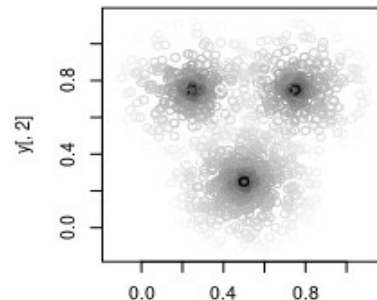
color=X1



color=X2

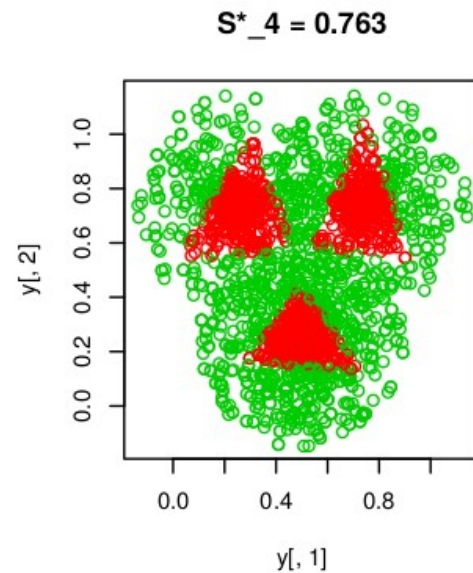
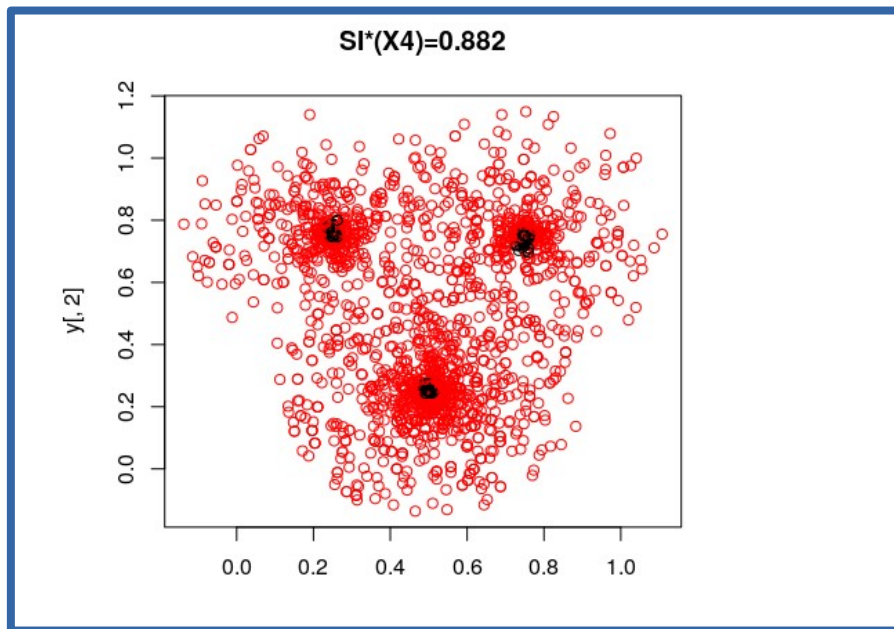


color=X3



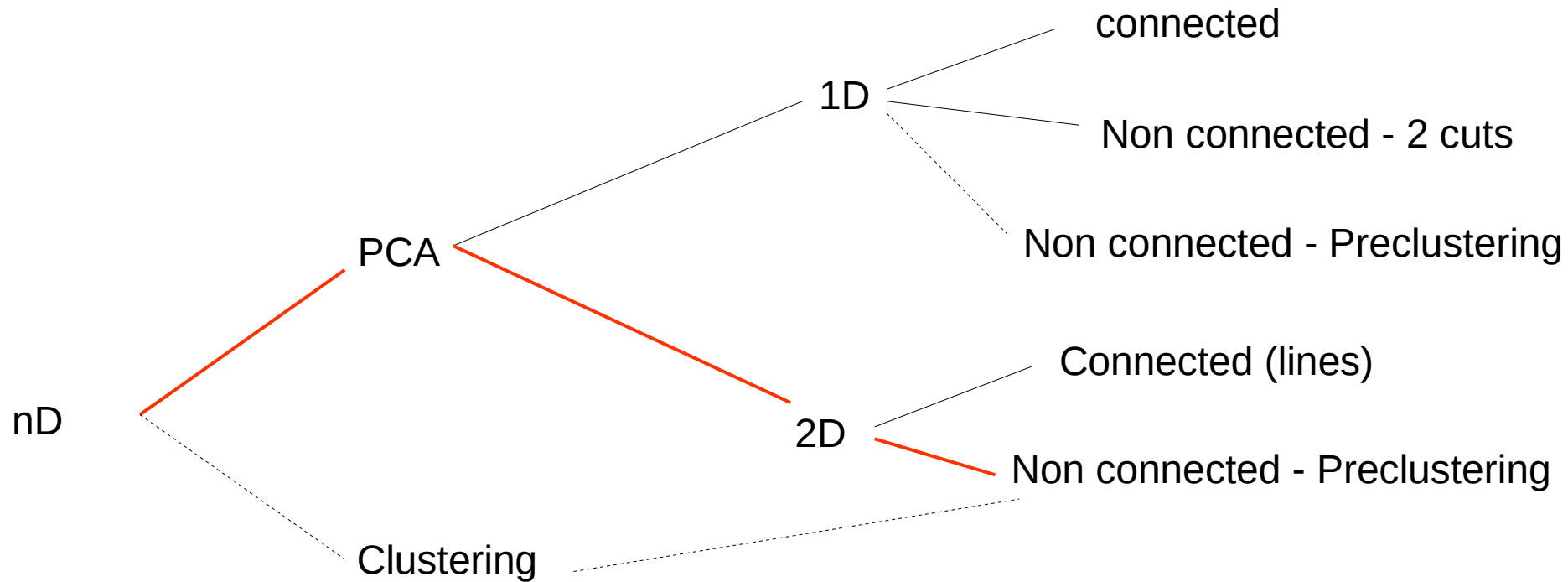
color=X4

**X4**  
**Cut=0.1**  
**K'=13**

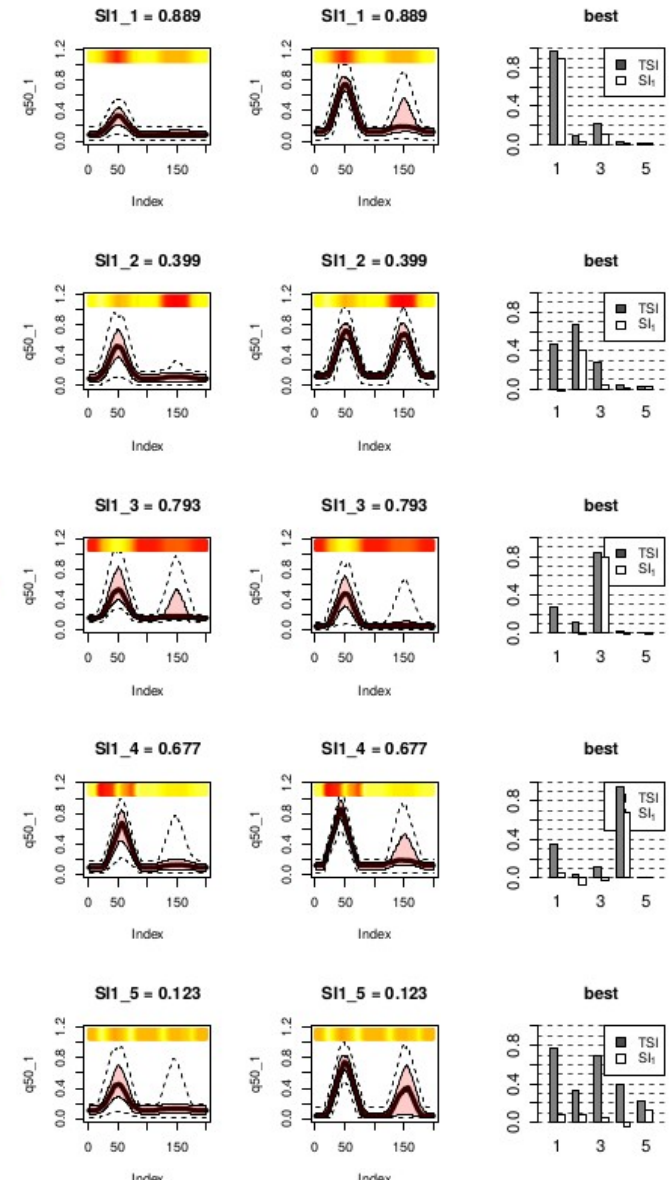
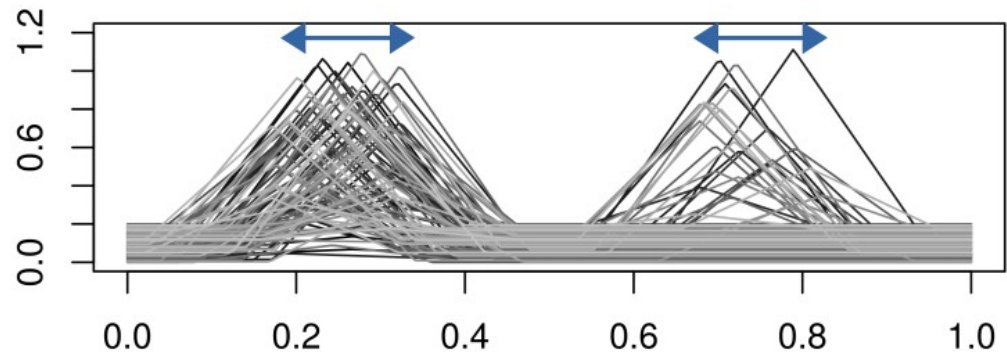


(ancienne approche)

# nD numerical example: ToyCurve



# nD numerical ToyCurve



# Perspectives

- CB-GSA : applications on environmental models (crop mixtures or hydrologic models)
  - => Key issues
    - DOE
    - Finding appropriate clustering (a priori or automatic)
- CB-GSA : Complementary analysis : intra-cluster and pure cluster transitions (which amounts to AS with dependent inputs)
- Sensitivity-driven clustering : test on a realistic model with MV outputs
- Sensitivity driven clustering : more efficient algorithms ??